

## **Code for starting program**

- `from cs1robots import *`
- `create_world()`
- `load_world("./worlds/...")`
- `hubo = Robot()`
- `hubo = Robot(color = "gray", orientation = 'E', beepers = 0, avenue = 1, street = 1)`

## **Movement methods**

- `hubo.turn_left()`
- `hubo.move()`
- `hubo.set_trace(color = "blue")`

## **Direction methods**

- `hubo.front_is_clear()`
- `hubo.left_is_clear()`
- `hubo.right_is_clear()`
- `hubo.facing_north()`

## **Beeper methods**

- `hubo.drop_beeper()`
- `hubo.pick_beeper()`
- `hubo.carries_beepers()`
- `hubo.on_beeper()`